

### 2.1 Angle Measures

## ○ Objective:

- I will be able to identify angle types, convert between degrees and radians for angle measures, identify coterminal angles, find the length of an intercepted arc, and find linear and angular
○ Vocabulary:

| Angle | Initial side | Terminal side | Vertex | Standard <br> position |
| :--- | :--- | :--- | :--- | :--- |
| Positive angles | Negative <br> angles | Quadrantal <br> angle | Degrees | Acute angle |
| Right angle | Obtuse angle | Straight angle | Radian | Central/Angle |
| Radian | Coterminal | Linear Speed | Angular Speed |  |
| Measure | angles |  |  |  |

### 2.1 Angle Measures

- Recognize and use the vocabulary of angles
- An angle ( $\alpha, \beta, \theta$, etc.) is formed by two rays that have a common endpoint. One ray is called the initial side and the other the terminal side.


FIGURE 5.2 An angle; two rays with a common endpoint

### 2.1 Angle Measures

- Standard position: vertex is at the origin of the coordinate system and the initial ray is on the $x$ axis.
- Sign
- Positive angles are generated by rotating counterclockwise.
- Negative angles are generated by rotating clockwise.


### 2.1 Angle Measures

- Types
- If the terminal ray is between axes, it lies in that quadrant.
- If the terminal ray is ON the x-axis or y-axis, it is a quadrantal angle


### 2.1 Angle Measures

- Use degree measure
- If the terminal ray has gone in a complete circle and is back on the initial angle, it has gone $360^{\circ}$.
- $1^{\circ}=1 / 360$ complete rotation

(a) Acute angle ( $0^{\circ}<\theta<90^{\circ}$ )

(b) Right angle ( $\frac{1}{4}$ rotation)

(c) Obtuse angle ( $90^{\circ}<\theta<180^{\circ}$ )

(d) Straight angle
( $\frac{1}{2}$ rotation)

FIGURE 5.5 Classifying angles by their degree measurement

### 2.1 Angle Measures

- Using radian measure

- One radian is the measure of the central angle of a circle that intercepts an arc equal in length to the radius of the circle.
- The radian measure of any central angle is the length of the intercepted arc divided by the circle's radius.

$$
\theta=\frac{\text { length of the intercepted arc }}{\text { radius }}=\frac{s}{r} \text { radians }
$$

### 2.1 Angle Measures

- Convert between degrees and radians
- To convert degrees to radians, multiply degrees by $\pi$ radians $/ 180^{\circ}$
- To convert radians to degrees, multiply radians by $180 \%$ radians


### 2.1 Angle Measures

- Draw angles in standard position
- It is important to learn to recognize angles in the coordinate plane by radians - start learning the unit circle!



### 2.1 Angle Measures

- Find coterminal angles
- Two angles with the same initial and terminal sides but possibly different rotations are called coterminal angles.
- Every angle has infinitely many coterminal angles.
- Increasing or decreasing the degree measure by an integer multiple of $360^{\circ}$ (or a radian measure by a multiple of $2 \pi$ ) results in a coterminal angle
- Positive and negative angles whose absolute values add up to $2 \pi$ are coterminal angles.


### 2.1 Angle Measures

- Find the length of a circular arc
- Can use the radian measure formula $\theta=s / r$ to find the length of the intercepted arc, s.

$$
s=r \theta
$$

### 2.1 Angle Measures

- Use linear and angular speed to describe circular motion
- If a point is in motion on a circle of radius $r$ through an angle of $\theta$ radians in time $t$, then its linear speed is $v=s / t$
- Its angular speed is $\omega=\theta / t$
- Linear speed is the product of the radius and the angular speed.

$$
s / t=(r \theta) / t=r^{*} \theta / t
$$

$v=r \omega$

### 2.2 Right Triangle Trigonometry

- Objective:
- I will be able to calculate trigonometric functions of acute angles. I will be able to solve for sides and angles of right triangles.

○ Vocabulary:

| Trigonometry | Hypotenuse | Sine of $\theta$ | $\operatorname{Cosine~of~} \theta$ | Tangent of $\theta$ |
| :--- | :--- | :--- | :--- | :--- |
| Cosecant of $\theta$ | Secant of $\theta$ | Cotangent of <br> $\theta$ | SOHCAHTOA | Pythagorean <br> Theorem |

### 2.2 Right Triangle Trigonometry

- Use right triangles to evaluate trigonometric functions
- Trigonometry means "measurement of triangles" and is used in navigation, building, and engineering.
- There are six main trigonometric functions and three inverse functions.
- Inputs are measures of acute angles in right triangles


### 2.2 Right Triangle Trigonometry

- Position of angle in triangle is very important.

- Names of the functions are words rather than letters.
- Functions represent ratios of sides in a right triangle.


### 2.2 Right Triangle Trigonometry



Sine
Cosine
"Some Old Hog Came Around Here and Took Our Apples."

### 2.2 Right Triangle Trigonometry

| Primary <br> Name | Abbrev. | Reciprocal <br> Name | Abbrev. | Inverse <br> Name | Abbrev. |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\operatorname{sine}$ | $\sin$ | cosecant | $\csc$ | arcsine | $\sin ^{-1}$ |
| cosine | $\cos$ | secant | $\sec$ | arccosine | $\cos ^{-1}$ |
| tangent | tan | cotangent | $\cot$ | arctangent | $\tan ^{-1}$ |

$$
\begin{array}{ccc}
\sin \theta=\frac{\text { Opposite }}{\text { Hypotenuse }} & \cos \theta=\frac{\text { Adjacent }}{\text { Hypotenuse }} & \tan \theta=\frac{\text { Opposite }}{\text { Adjacent }} \\
\csc \theta=\frac{\text { Hypotenus }}{\text { Opposite }} & \sec \theta=\frac{\text { Hypotenus }}{\text { Adjacent }} & \cot \theta=\frac{\text { Adjacent }}{\text { Opposite }} \\
\sin ^{-1}\left(\frac{\text { Opposite }}{\text { Hypotenuse }}\right)=\theta & \cos ^{-1}\left(\frac{\text { Adjacent }}{\text { Hypotenuse }}\right)=\theta & \sin ^{-1}\left(\frac{\text { opposite }}{\text { Adjacent }}\right)=\theta
\end{array}
$$

### 2.2 Right Triangle Trigonometry

- Primary and Reciprocal functions are used to find sides while inverse functions are used to find angle measures.
- The trigonometric function values of $\theta$ depend only on the size of angle $\theta$ and not on the size of the triangle.


### 2.2 Right Triangle Trigonometry

- Pythagorean Theorem
- The sum of the squares of the legs of a right triangle equals the square of the length of the hypotenuse ( ).
- Requires all three sides to evaluate all six functions.
- Remember to rationalize the denominator when necessary.


### 2.2 Right Triangle Trigonometry

$\odot$ Find function values for $30^{\circ}$, $45^{\circ}$ ( and $60^{\circ}$ (

- Start studying the outside of the Unit Circle for sine and cosine of common angles.
- If you must find the reciprocal, do so before rationalizing the denominator.


### 2.2 Right Triangle Trigonometry

| $\boldsymbol{\theta}$ | $\mathbf{3 0 ^ { \circ } = ( \frac { \pi } { 6 } ) ,}$ | $\mathbf{4 5 ^ { \circ }}=\left(\frac{\pi}{4}\right)$ | $\mathbf{6 0 ^ { \circ }}=\left(\frac{\pi}{3}\right)$ |
| :---: | :---: | :---: | :---: |
| $\sin \theta$ | $\frac{1}{2}$ | $\frac{\sqrt{2}}{2}$ | $\frac{\sqrt{3}}{2}$ |
| $\cos \theta$ | $\frac{\sqrt{3}}{2}$ | $\frac{\sqrt{2}}{2}$ | $\frac{1}{2}$ |
| $\tan \theta$ | $\frac{\sqrt{3}}{3}$ | 1 | $\sqrt{3}$ |
|  |  |  |  |

### 2.3 Trigonometric Identities

○ Objective:

- I will be able to use trigonometric identities to find the values of the six main trigonometric functions for an angle.

○ Vocabulary:

| Trigonometric <br> Identities | Reciprocal <br> identities | Quotient <br> Identities | Pythagorean <br> Identities | Complements |
| :--- | :--- | :--- | :--- | :--- |
| Cofunctions |  |  |  |  |

### 2.3 Trigonometric Identities

- Recognize and Use Fundamental Identities
- Trigonometric identities are relationships between trigonometric functions
- Identities can be used to find related trigonometric functions.


### 2.3 Trigonometric Identities

- Reciprocal Identities

$$
\begin{array}{ll}
\sin \theta=\frac{1}{\csc \theta} & \csc \theta=\frac{1}{\sin \theta} \\
\cos \theta=\frac{1}{\sec \theta} & \sec \theta=\frac{1}{\cos \theta} \\
\tan \theta=\frac{1}{\cot \theta} & \cot \theta=\frac{1}{\tan \theta}
\end{array}
$$

### 2.3 Trigonometric Identities

- Quotient Identities

$$
\tan \theta=\frac{\sin \theta}{\cos \theta} \quad \cot \theta=\frac{\cos \theta}{\sin \theta}
$$

- Pythagorean Identities
$\sin ^{2} \theta+\cos ^{2} \theta=1$

$$
1+\tan ^{2} \theta=\sec ^{2} \theta
$$

$$
1+\cot ^{2} \theta=\csc ^{2} \theta
$$

### 2.3 Trigonometric Identities

○ Use equal cofunctions of complements

- Two positive angles are complements if their sum is $90^{\circ}$ or
- Cofunctions:
- Any pair of trigonometric functions and for which

$$
f(\theta)=g\left(90^{\circ}-\theta\right) \text { and } g(\theta)=f\left(90^{\circ}-\theta\right)
$$

### 2.3 Trigonometric Identities

- Cofunction Identities

$$
\begin{array}{ll}
\sin \theta=\cos \left(90^{\circ}-\theta\right) & \cos \theta=\sin \left(90^{\circ}-\theta\right) \\
\tan \theta=\cot \left(90^{\circ}-\theta\right) & \cot \theta=\tan \left(90^{\circ}-\theta\right) \\
\sec \theta=\csc \left(90^{\circ}-\theta\right) & \csc \theta=\sec \left(90^{\circ}-\theta\right)
\end{array}
$$

If $\theta$ is in radians, replace $90^{\circ}$ with $\pi / 2$

### 2.4 Applications of Trigonometry

© Objective:

- I will understand elevation and depression, be able to identify angles of elevation and depression. I will be able to apply these concepts to real-world applications.
○ Vocabulary:
Angle of elevation
Angle of depression


### 2.4 Applications of Trigonometry

$\odot$ Use right triangle trigonometry to solve applied problems

- Many applications of right triangle trigonometry involve the angle made with an imaginary horizontal line.
$\circ$ The angle above the horizontal is called the angle of elevation.
- The angle below the horizontal is called the angle of depression.


### 2.4 Applications of Trigonometry



- Note: the vertex of the angle can be to the right or to the left.


### 2.5 Reference Angles

○ Objective:

- I will be able to find a reference angle for obtuse angles. I will be able to use the reference angle to evaluate trigonometric functions of obtuse angles.
○ Vocabulary:
Reference angles



### 2.5 Reference Angles

- Find Reference Angles
- Trigonometric functions of positive obtuse angles and all negative angles, are evaluated by making use of a positive acute angle.
- Reference angle - the positive acute angle $\theta^{\prime}$ formed by the terminal side of $\theta$ and the xaxis.





### 2.5 Reference Angles



If $90^{\circ}<\theta<180^{\circ}$,
then $\theta^{\prime}=180^{\circ}-\theta$.


If $180^{\circ}<\theta<270^{\circ}$, then $\theta^{\prime}=\theta-180^{\circ}$.


If $270^{\circ}<\theta<360^{\circ}$, then $\theta^{\prime}=360^{\circ}-\theta$.

### 2.5 Reference Angles

- Finding reference angles for angles greater than $360^{\circ}(2 \pi)$ or less than $-360^{\circ}(-2 \pi)$
- Find a positive angle a less than $360^{\circ}$ or $2 \pi$ that is coterminal with the given angle.
- Draw $\alpha$ in standard position.
- Use the drawing to find the reference angle for the given angle. The positive acute angle formed by the terminal side of $\alpha$ and the $x$ axis is the reference angle.


### 2.5 Reference Angles

© Use reference angles to evaluate trigonometric functions

- The values of the trigonometric functions of a given angle, $\theta$, are the same as the values of the trigonometric functions of the reference angle, $\theta^{\prime}$, except possibly for the sign


### 2.5 Reference Angles

- Procedure for using reference angles to evaluate trigonometric functions:
- Find the associated reference angle, $\theta^{\prime}$, and the function value for $\theta^{\prime}$.
- Use the quadrant in which $\theta$ lies to prefix the appropriate sign to the function value in the first step.


### 2.5 Reference Angles

$\bigcirc$ Use the signs of the trigonometric functions

- If $\theta$ is not a quadrantal angle, the sign of a trigonometric function depends on the quadrant in which $\theta$ lies.
- Quadrant I: all functions are positive
- Quadrant II: sine and cosecant are positive
- Quadrant III: tangent and cotangent are positive
- Quadrant IV: cosine and secant are positive


### 2.5 Reference Angles

A

All trig functions are positive in

QI.

Smart

Sine and its reciprocal, cosecant, are positive in QII.

Trig

Tangent and its reciprocal, cotangent, are positive in QIII.

## Class.

Cosine and its reciprocal, secant, are positive in QIV.

### 2.6 Trigonometric Functions

○ Objective:

- I will be able to use the definition of trigonometric functions of any angle to evaluate trig functions for any angle. I will be able to determine the sign of a trig function given the quadrant in which lies the terminal side of the angle.


### 2.6 Trigonometric Functions

- Use the definition of trigonometric functions of any angle
- In the examples below, the angles are in standard position, and $P(x, y)$ is $r$ units from the origin on the terminal side of $\theta$.
- A right triangle is formed by drawing the line segment from $P$ perpendicular to the $x$-axis. In this case, y is opposite $\theta$, and x is adjacent to $\theta$.


### 2.6 Trigonometric Functions


(a) $\theta$ lies in
quadrant I .

(b) $\theta$ lies in
quadrant II.

(c) $\theta$ lies in quadrant III.

(d) $\theta$ lies in quadrant IV

### 2.6 Trigonometric Functions

- Definitions of Trigonometric Functions of Any Angle
- $P(x, y)$ is any point on the terminal side other than the origin.
- $r=\sqrt{ }(x+y)$ (the distance from the origin to $P$ )
- The six trigonometric ratios of $\theta$ are defined by the following ratios:

$$
\begin{array}{cc}
\sin \theta=\frac{y}{r} & \csc \theta=\frac{r}{y} ; y \neq 0 \\
\cos \theta=\frac{x}{r} & \sec \theta=\frac{r}{x} ; x \neq 0 \\
\tan \theta=\frac{y}{x} ; x \neq 0 & \cot \theta=\frac{x}{y} ; y \neq 0
\end{array}
$$

